

Discrete-time deterministic models

Modern Techniques in Modelling

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Introduction

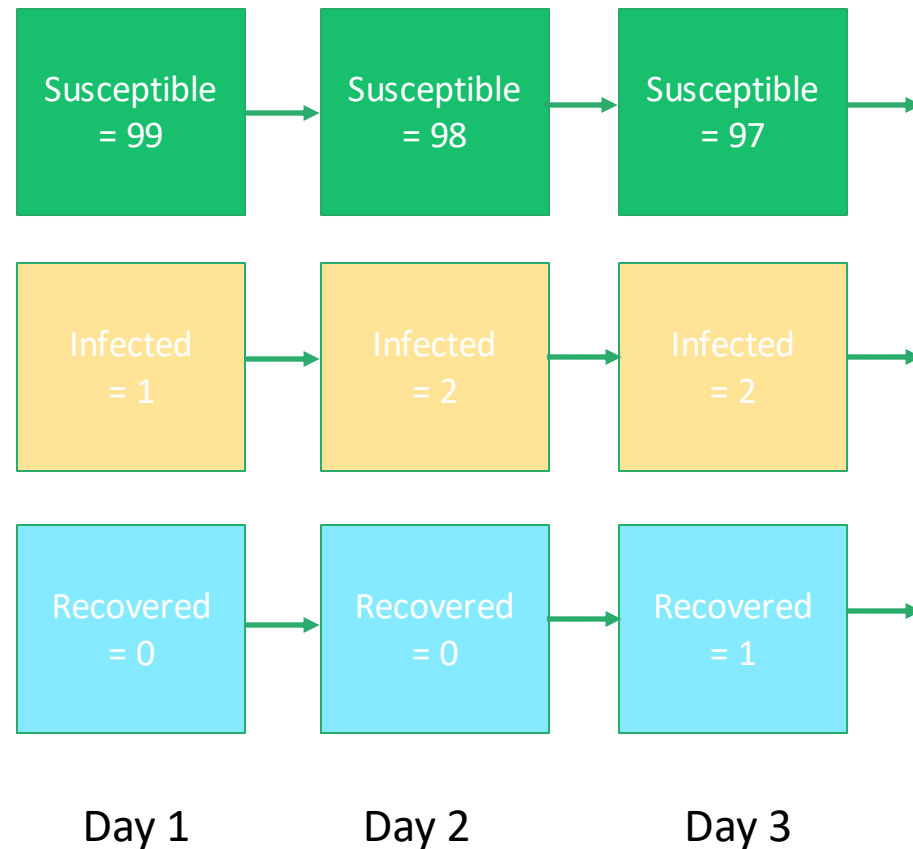
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- Welcome to the lecture on Discrete-time deterministic models
- This session's objectives:
 - Understand the concept of discrete-time models
 - Learn about difference equations
 - Explore the SIR (Susceptible-Infectious-Recovered) model in discrete time
 - Implement and analyse a discrete-time SIR model in R

Discrete-time deterministic models

Often we may want to model an epidemic in terms of a discrete time step, e.g. from one day to the next:



This can be modelled by considering the current state of the epidemic, y , at time t :

$$\mathbf{y}(t) = (S(t), I(t), R(t))$$

that updates with each time step by some function of the current state:

$$\mathbf{y}(t + 1) = \mathbf{y}(t) + g(\mathbf{y}(t))$$

This is known generally as a **difference equation**, the solution of which can be solved exactly by iteratively applying the update function for each discrete time step.

Example: If you have £100 in a bank account and earn 5% interest yearly, next year you'd have: $£100 * (1 + 0.05) = £105$

Consider an SIR model for a closed population that follows the following rules:

- Susceptible individuals become **infected** at a rate proportional to the size of the product of *susceptible* and *infectious* populations:

$$S(t + 1) = S(t) - \beta * S(t) * I(t)$$

where β is the per capita infection rate.

- **Recovery** from infection grants life-long immunity

$$R(t + 1) = R(t) + \gamma * I(t)$$

Where γ is the recovery rate.

(The mean time spent infectious is then $1/\gamma$ (1/rate = duration)).

The only transitions between states in our model are **infection** and **recovery**

$$I(t + 1) = I(t) + \beta * S(t) * I(t) - \gamma * I(t)$$

Which adds those being **infected** and subtracts those who **recover**

We start with:

- 1% of the population are infected, $I(0) = 0.01$
- no recovered, $R(0) = 0$, and
- the remainder of the population is susceptible, $S(0) = 0.99$,
- for $N(t) = 1$, the total population.

Our system is therefore:

$$\begin{aligned} S(t+1) &= S(t) - \beta * S(t) * I(t), & S(0) &= 0.99 \\ I(t+1) &= I(t) + \beta * S(t) * I(t) - \gamma * I(t), & I(0) &= 0.01 \\ R(t+1) &= R(t) + \gamma * I(t), & R(0) &= 0 \end{aligned}$$

SIR example

This system can also be written in vector form as:

$$\begin{bmatrix} S \\ I \\ R \end{bmatrix}_{t+1} = \begin{bmatrix} S \\ I \\ R \end{bmatrix}_t + \begin{bmatrix} -\beta SI \\ \beta SI - \gamma I \\ \gamma I \end{bmatrix}_t$$

Here the subscript indicates the time value and the term on the right is our *update vector*.

SIR example

In R, we can write a function to return our update vector with three elements:

```
update_sir <- function(t, y, parms){  
  S <- y[1]  
  I <- y[2]  
  R <- y[3]  
  
  beta <- parms['beta']  
  gamma <- parms['gamma']  
  
  out <- c(- beta*S*I,  
           + beta*S*I - gamma*I,  
           + gamma*I)  
  
  return(out)  
}
```

Discrete-time deterministic SIR

```
parms_sir <- c(beta = 1.3,  
              gamma = 0.23)  
  
time_sir <- seq(0, 20, by = 1)  
  
y_sir <- matrix(data = NA,  
               nrow = length(time_sir),  
               ncol = 3)  
  
# initial values at t=0  
y_sir[1, ] <- c(0.99, 0.01, 0)  
  
for (i in 2:(nrow(y_sir))) {  
  
  y_sir[i, ] <- y_sir[i - 1, ] +  
    update_sir(t = time_sir[i],  
              y = y_sir[i - 1, ],  
              parms = parms_sir)  
  
}
```

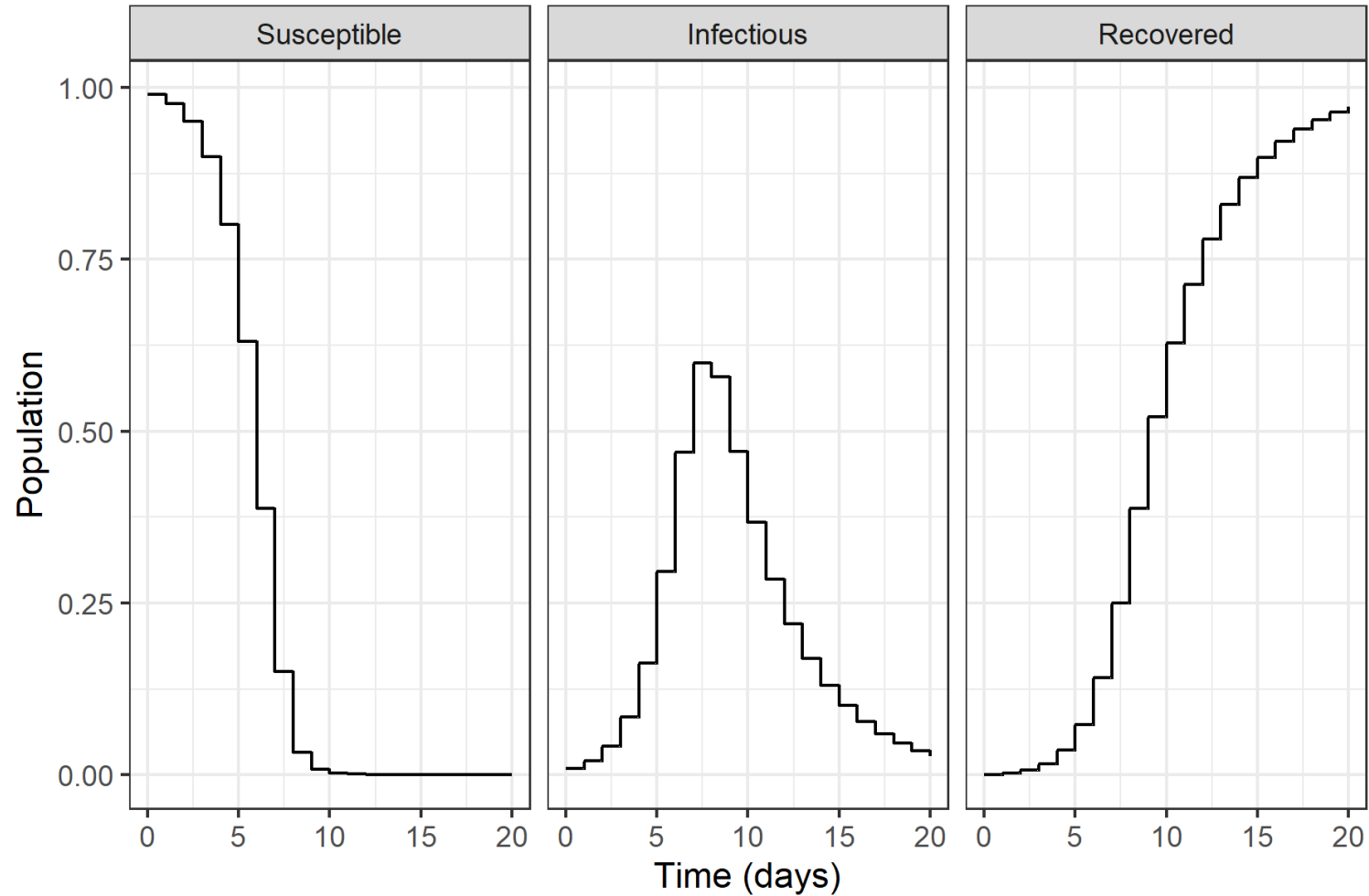
Discrete-time deterministic SIR

```
y_sir_df <- as.data.frame(y_sir)
names(y_sir_df) <- c('Susceptible',
                    'Infectious',
                    'Recovered')
y_sir_df <- cbind(time = time_sir,
                 y_sir_df)
```

```
head(y_sir_df)
```

##	time	Susceptible	Infectious	Recovered
## 1	0	0.9900000	0.0100000	0.0000000
## 2	1	0.9771300	0.0205700	0.0023000
## 3	2	0.9510006	0.0419683	0.0070311
## 4	3	0.8991151	0.0842011	0.0166838
## 5	4	0.8006967	0.1632533	0.0360501
## 6	5	0.6307654	0.2956363	0.0735983

Discrete-time deterministic SIR



Our more general form of the update is

$$\mathbf{y}(t + 1) = f(t, \mathbf{y}(t), \boldsymbol{\theta}(t))$$

...but parameters may or may not change with time t .

Summary

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- Difference equations are defined for discrete time steps, and can be solved by iterating over those time steps.
- Discrete time models can be specified either as:

$\mathbf{y}(t + \Delta t) = f(\mathbf{y}(t), t, \boldsymbol{\theta}, \Delta t)$ to transform current state

$\mathbf{y}(t + \Delta t) = \mathbf{y}(t) + \Delta t g(\mathbf{y}(t), t, \boldsymbol{\theta})$ to update current state

- $f(\cdot), g(\cdot)$ can be any function that captures the dynamics of the physical system we're interested in.

- We'll now look at implementing discrete-time models in R in the practical.
- Later today you'll start to learn about extending to continuous time models with **differential equations**.
- Later in the week you'll learn about update functions that model infection and recovery as probabilistic events.



Practical

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